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DT Lee, CD Yang, CK Wong - IEEE Transactions on Computers, 1994 - portal.acm.org  
 ... layer distance (xy-distance) minimum-bend **path** in optimal ...  $O(e \log e)$  time using  $O(e \log e)$  **space**. ... Optimal two-terminal **routing**, Integration, the ...  
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I Stojmenovic, X Lin - IEEE Transactions on Parallel and Distributed Systems, 2001 - doi.ieeecs.org  
 ... The single-**path** approach is also followed in [19 ... to identify the best GPS-based **routing** protocols for ... nodes positioned in a three-dimensional **space** and **obstacles** ...  
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#### Pipe Routing= Path Planning (with Many Constraints)

D Zhu, JC Latombe - ieeexplore.ieee.org  
 ... The algorithm computing time **path**  $L_{\infty}$  of IL5 consists of ... Approximate the free **space** ...  
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#### A Monte-Carlo algorithm for path planning with many degrees of freedom - group of 2 »

J Barraquand, JC Latombe - Robotics and Automation, 1990. Proceedings., 1990 IEEE ... , 1990 - ieeexplore.ieee.org  
 ... the traveling salesman problem and the placement/**routing** of VLSI ... is so cluttered that the solution **path** has to ... close to the boundary of the free **space** (or in ...  
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#### Dynamic global path planning with uncertainty for mobile robots in manufacturing

H Hu, M Brady - Robotics and Automation, IEEE Transactions on, 1997 - ieeexplore.ieee.org  
 ... in such problems is to find the **route** between two ... **space**, and  $X$  is the state **space** (or nodes in ... say described by  $W$ . For a predefined **path**, unexpected **obstacles** ...  
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#### Path finding for human motion in virtual environments - group of 3 »

S Bandi, D Thalmann - Computational Geometry: Theory and Applications, 2000 - Elsevier  
 ... **obstacles**. A collision free **path** is computed by searching the regions of configuration **space** free of configuration **space** **obstacles**. The ...  
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#### TWIGY-a topological algorithm based routing system - group of 2 »

MT Doreau, P Koziol - Proceedings of the 18th conference on Design automation, 1981 - portal.acm.org  
 ... 3. Solution/Physical **Space** Relationship ... These are "conventional" **routing** **obstacles**. ... The task of the Drawer is to find a **path** through the scratchpad maze ...  
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#### [PS] Rectilinear Paths Among Rectilinear Obstacles - group of 6 »

DT Lee, CD Yang, CK Wong - Discrete Applied Mathematics, 1996 - iis.sinica.edu.tw  
 ... rst one nding a shortest **path** between two points on a **routing** plane with ...  $O(m^2)$   
**space** to represent an mm ...  $O(l^2)$  for nding a **path** crossing  $l$  grid points. ...  
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[PS] **Rectilinear Path Problems among Rectilinear Obstacles Revisited** - group of 7 »  
 CD Yang, DT Lee, CK Wong - SIAM J. Comput., 1995 - homepage.iis.sinica.edu.tw  
 ... time and **space**. Key words. ... Both measures, the number of bends and the length of a  
 rectilinear **path**, are two important factors while **routing** between two ...  
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**Optimal buffered routing path constructions for single and multiple clock domain systems** - group of 10 »

S Hassoun, CJ Alpert, M Thiagarajan - Proceedings of the 2002 IEEE/ACM international conference on  
 ..., 2002 - doi.ieeecomputersociety.org  
 ... The Fast **Path** algorithm finds the minimum delay source-to-sink buffered **routing**  
**path**, while considering both physical **obstacles** (eg, due to IP, memories, and ...  
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state-space. In the **routing** plane then, we have a starting point, s, to be connected to a ... **cost** of a **path** from s to a **node** n as (n). Notice that ...[ieeexplore.ieee.org/iel5/10570/33447/01585771.pdf?arnumber=1585771](http://ieeexplore.ieee.org/iel5/10570/33447/01585771.pdf?arnumber=1585771) - [Similar pages](#)[ [More results from ieeexplore.ieee.org](#) ]**[PDF] Curved Edge Routing**

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method is summarized in the algorithm routeEdges. algorithm routeEdges. Build the initial **cost** function corresponding to **nodes**. for each **path** P. **Route** P ...[www.springerlink.com/index/ECH26VFF5LJD7GJ3.pdf](http://www.springerlink.com/index/ECH26VFF5LJD7GJ3.pdf) - [Similar pages](#)**[Paper] Optimal Path Planning using an Improved A\* Algorithm for ...**The **nodes** are evaluated by combining g(n), the **cost** to reach the goal, ... In this work it was possible to infer a safe **path** avoiding the **obstacles** ...[www.actapress.com/PDFViewer.aspx?paperId=23162](http://www.actapress.com/PDFViewer.aspx?paperId=23162) - [Similar pages](#)**[PPT] www.cs.utk.edu/~parker/Courses/CS594-fall04/Lectur...**File Format: Microsoft Powerpoint - [View as HTML](#)Finding **path** between initial **node** and goal **node** can be done using graph search ...Converts world **space** to a configuration **space**; Use **obstacle** growing to ...[Similar pages](#)**[PDF] A Minimum Cost Path Search Algorithm Through Tile Obstacles**

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Shortest **path** search, VLSI **routing**. 1. INTRODUCTION. In this paper, we look at the

problem of minimum **cost path**. searching through rectilinear **obstacles**. ...  
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6 Mbps over direct **path**; 9 Mbps over two-hop **path**! • Multihop benefit even greater in non-free-**space** environments. and/or when **routing** around **obstacles** ...

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Place waypoints at every convex corner of the **obstacles** ... Now we are expanding **nodes** according to best estimated total **path cost**. Is it optimal? ...

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technique defines the space between **obstacles** on the board as a series of rectangles. ... from the **routing space** the topological router is able to map more ...

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to the **routing space**; the potential path simply weaves its way between each pair of **obstacles**, as shown in Figure 3. The topological map removes the ...www.altium.com/files/learningguides/dxp/wp\_situs.pdf - [Similar pages](#)[\[PDF\] Application of an EACS algorithm to \*\*obstacle\*\* detour routing in ...](#)

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**obstacles** distributed in a rectangular chip area to be routed ... **routing space** can be defined by an undirected graph  $G=(V, E)$ , ...ieeexplore.ieee.org/iel5/8907/28158/01259742.pdf - [Similar pages](#)[\[PDF\] Neural global router - Neural Networks, 2000. IJCNN 2000 ...](#)

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'Where, channel is the horizontal **routing space**, between two rows of **obstacles** and feedthrough is the vertical **routing space** between two. **obstacles**. ...ieeexplore.ieee.org/iel5/6927/18647/00859447.pdf - [Similar pages](#)[\[ More results from ieeexplore.ieee.org \]](#)[\[PDF\] Design Rules Driven Shape Based Gridless Routing Easy-Router ...](#)File Format: PDF/Adobe Acrobat - [View as HTML](#)of **obstacles** within the design can be identified and avoided dur- ... mate shapes which wastes valuable **routing space** and potential. routing area. ...www.numberone.com/downloads/datasheets/Easy-Router.pdf - [Similar pages](#)[\[PDF\] The Oct-Touched Tile: A New Architecture for Shape-Based Routing](#)

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the segments of routed wires are regarded as **obstacles** for. the rest of nets. ... If the **routing space** is multi-layer, we assign vias. on tiles. ...ietfec.oxfordjournals.org/cgi/reprint/E89-A/2/448.pdf - [Similar pages](#)[\[PDF\] Magic Tutorial #7: Netlists and Routing](#)File Format: PDF/Adobe Acrobat - [View as HTML](#)Unless you have extra **routing space** in your chip, you may have to make slight re- ... The router tends to have special difficulties with **obstacles** running ...web.mit.edu/magic-vlsi\_v7.4/pdfdoc/tut7.pdf - [Similar pages](#)[\[PDF\] A Depth-First-Search Controlled Gridless Incremental Routing ...](#)File Format: PDF/Adobe Acrobat - [View as HTML](#)ing in the available **routing space** without disturbing existing net ... **obstacles** and existing nets in the routing region, and then a search ...www.iccd-conference.org/proceedings/2004/22310086.pdf - [Similar pages](#)

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**routing space**. This can be done using either the point-based. or the tile-based approach.

... gular **obstacles** in the routing region according to wire/via ...

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resented by edges; as there is finite **routing space** on the borders, ... with **obstacles**; as

our benchmarks do not contain **obstacles**, this ...

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